# NAG Fortran Library Routine Document

### G02DGF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

# 1 Purpose

G02DGF calculates the estimates of the parameters of a general linear regression model for a new dependent variable after a call to G02DAF.

# 2 Specification

```
SUBROUTINE GO2DGF(WEIGHT, N, WT, RSS, IP, IRANK, COV, Q, LDQ, SVD, P, Y,
B, SE, RES, WK, IFAIL)

INTEGER

N, IP, IRANK, LDQ, IFAIL

WT(*), RSS, COV(IP*(IP+1)/2), Q(LDQ,IP+1),
P(IP*IP+2*IP), Y(N), B(IP), SE(IP), RES(N),
WK(5*(IP-1)+IP*IP)

LOGICAL
CHARACTER*1

WEIGHT
```

# 3 Description

G02DGF uses the results given by G02DAF to fit the same set of independent variables to a new dependent variable.

G02DAF computes a QR decomposition of the matrix of p independent variables and also, if the model is not of full rank, a singular value decomposition (SVD). These results can be used to compute estimates of the parameters for a general linear model with a new dependent variable. The QR decomposition leads to the formation of an upper triangular p by p matrix R and an n by n orthogonal matrix Q. In addition the vector  $c = Q^T y$  (or  $Q^T W^{1/2} y$ ) is computed. For a new dependent variable,  $y_{\text{new}}$ , G02DGF computes a new value of  $c = Q^T y_{\text{new}}$  or  $Q^T W^{1/2} y_{\text{new}}$ .

If R is of full rank, then the least-squares parameter estimates,  $\hat{\beta}$ , are the solution to

$$R\hat{\beta} = c_1,$$

where  $c_1$  is the first p elements of c.

If R is not of full rank, then G02DAF will have computed an SVD of R,

$$R = Q_* \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} P^T,$$

where D is a k by k diagonal matrix with non-zero diagonal elements, k being the rank of R, and  $Q_*$  and P are p by p orthogonal matrices. This gives the solution

$$\hat{\beta} = P_1 D^{-1} Q_{*,}^T c_1,$$

 $P_1$  being the first k columns of P, i.e.,  $P = (P_1 P_0)$ , and  $Q_{*_1}$  being the first k columns of  $Q_*$ . Details of the SVD are made available by G02DAF in the form of the matrix  $P^*$ :

$$P^* = \begin{pmatrix} D^{-1} P_1^T \\ P_0^T \end{pmatrix}.$$

The matrix  $Q_*$  is made available through the workspace of G02DAF.

In addition to parameter estimates, the new residuals are computed and the variance-covariance matrix of the parameter estimates are found by scaling the variance-covariance matrix for the original regression.

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#### 4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Hammarling S (1985) The singular value decomposition in multivariate statistics SIGNUM Newsl. **20 (3)** 2–25

Searle S R (1971) Linear Models Wiley

## 5 Parameters

#### 1: WEIGHT – CHARACTER\*1

Input

On entry: indicates if weights are to be used.

If WEIGHT = 'U' (Unweighted), least-squares estimation is used.

If WEIGHT = 'W' (Weighted), weighted least-squares is used and weights must be supplied in the array WT.

Constraint: WEIGHT = 'U' or 'W'.

2: N – INTEGER

Input

On entry: the number of observations, n.

Constraint:  $N \ge IP$ .

3: WT(\*) - real array

Input

On entry: if WEIGHT = 'W', then WT must contain the weights to be used in the weighted regression.

If WT(i) = 0.0, then the *i*th observation is not included in the model, in which case the effective number of observations is the number of observations with non-zero weights.

If WEIGHT = 'U', then WT is not referenced and the effective number of observations is n.

Constraint: if WEIGHT = 'W', WT(i)  $\geq$  0.0, for i = 1, 2, ..., n.

4: RSS – real

Input/Output

On entry: the residual sum of squares for the original dependent variable.

On exit: the residual sum of squares for the new dependent variable.

Constraint: RSS > 0.0.

5: IP – INTEGER

Input

On entry: the number of independent variables (including the mean if fitted), p.

*Constraint*:  $1 \le IP \le N$ .

6: IRANK – INTEGER

Input

On entry: the rank of the independent variables, as given by G02DAF.

Constraints: IRANK > 0, and if SVD = .FALSE., then IRANK = IP, else IRANK < IP.

7: COV(IP\*(IP+1)/2) - real array

Input/Output

On entry: the covariance matrix of the parameter estimates as given by G02DAF.

On exit: the upper triangular part of the variance-covariance matrix of the IP parameter estimates given in B. They are stored packed by column, i.e., the covariance between the parameter estimate given in B(i) and the parameter estimate given in B(j),  $j \ge i$ , is stored in  $COV(j \times (j-1)/2 + i)$ .

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#### 8: Q(LDQ,IP+1) - real array

Input/Output

On entry: the results of the QR decomposition as returned by G02DAF.

On exit: the first column of Q contains the new values of c, the remainder of Q will be unchanged.

#### 9: LDQ – INTEGER

Input

On entry: the first dimension of the array Q as declared in the (sub)program from which G02DGF is called.

Constraint: LDQ  $\geq$  N.

10: SVD - LOGICAL

Input

On entry: indicates if a singular value decomposition was used by G02DAF.

If SVD = .TRUE., a singular value decomposition was used by G02DAF.

If SVD = .FALSE., a singular value decomposition was not used by G02DAF.

#### 11: P(IP\*IP+2\*IP) - real array

Input

On entry: details of the QR decomposition and SVD, if used, as returned in array P by G02DAF.

If SVD = .FALSE., only the first IP elements of P are used; these contain the zeta values for the QR decomposition (see F08AEF (SGEQRF/DGEQRF) for details).

If SVD = .TRUE., the first IP elements of P contain the zeta values for the QR decomposition (see F08AEF (SGEQRF/DGEQRF) for details) and the next IP  $\times$  IP + IP elements of P contain details of the singular value decomposition.

#### 12: Y(N) - real array

Input

On entry: the new dependent variable,  $y_{\text{new}}$ .

#### 13: B(IP) - real array

Output

On exit: the least-squares estimates of the parameters of the regression model,  $\hat{\beta}$ .

#### 14: SE(IP) – *real* array

Output

On exit: the standard error of the estimates of the parameters.

## 15: RES(N) - real array

Output

On exit: the residuals for the new regression model.

#### 16: WK(5\*(IP-1)+IP\*IP) - real array

Input

On entry: if SVD = .TRUE., WK must be unaltered from the previous call to G02DAF or G02DGF. If SVD = .FALSE., WK is used as workspace.

#### 17: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

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# 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
      On entry, IP < 1,
                N < IP
      or
                IRANK \leq 0,
      or
      or
                SVD = .FALSE. and IRANK \neq IP,
                SVD = .TRUE. and IRANK > IP,
      or
               LDQ < N,
      or
                RSS < 0.0,
      or
                WEIGHT \neq 'U' or 'W'.
      or
IFAIL = 2
      On entry, WEIGHT = 'W' or 'V' and a value of WT < 0.0.
```

# 7 Accuracy

The same accuracy as G02DAF is obtained.

# **8** Further Comments

The values of the leverages,  $h_i$ , are unaltered by a change in the dependent variable so a call to G02FAF can be made using the value of H from G02DAF.

## 9 Example

A data set consisting of 12 observations with four independent variables and two dependent variables are read in. A model with all four independent variables is fitted to the first dependent variable by G02DAF and the results printed. The model is then fitted to the second dependent variable by G02DGF and those results printed.

#### 9.1 Program Text

**Note:** the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO2DGF Example Program Text
Mark 14 Release. NAG Copyright 1989.
.. Parameters ..
                   MMAX, NMAX
TNTEGER
PARAMETER
                   (MMAX=5,NMAX=12)
                   NIN, NOUT
INTEGER
                   (NIN=5,NOUT=6)
PARAMETER
.. Local Scalars ..
real
                   RSS, TOL
INTEGER
                   I, IDF, IFAIL, IP, IRANK, J, M, N
LOGICAL
                   SVD
CHARACTER
                   MEAN, WEIGHT
.. Local Arrays ..
real
                   B(MMAX), COV(MMAX*(MMAX+1)/2), H(NMAX),
                   NEWY(NMAX), P(MMAX*(MMAX+2)), Q(NMAX,MMAX+1),
                   RES(NMAX), SE(MMAX), WK(5*(MMAX-1)+MMAX*MMAX),
                   \mathtt{WT}(\mathtt{NMAX}) , \mathtt{XM}(\mathtt{NMAX},\mathtt{MMAX}) , \mathtt{Y}(\mathtt{NMAX})
INTEGER
                   ISX(MMAX)
.. External Subroutines .
EXTERNAL
                   GO2DAF, GO2DGF
```

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```
.. Executable Statements ..
      WRITE (NOUT, *) 'GO2DGF Example Program Results'
      Skip heading in data file
      READ (NIN, *)
      READ (NIN,*) N, M, WEIGHT, MEAN
      IF (N.LE.NMAX .AND. M.LT.MMAX) THEN
         IF (WEIGHT.EQ.'W' .OR. WEIGHT.EQ.'w') THEN
            DO 20 I = 1, N
               READ (NIN, \star) (XM(I,J), J=1,M), Y(I), WT(I), NEWY(I)
   20
            CONTINUE
         ELSE
            DO 40 I = 1, N
               READ (NIN,*) (XM(I,J),J=1,M), Y(I), NEWY(I)
            CONTINUE
   40
         END IF
         READ (NIN,*) (ISX(J),J=1,M), IP
         Set tolerance
         TOL = 0.00001e0
         IFAIL = 0
         Fit initial model using GO2DAF
         CALL GO2DAF(MEAN, WEIGHT, N, XM, NMAX, M, ISX, IP, Y, WT, RSS, IDF, B, SE,
                      COV, RES, H, Q, NMAX, SVD, IRANK, P, TOL, WK, IFAIL)
         WRITE (NOUT, *) 'Results from GO2DAF'
         WRITE (NOUT, *)
         IF (SVD) THEN
            WRITE (NOUT,*) 'Model not of full rank'
            WRITE (NOUT, *)
         END IF
         WRITE (NOUT, 99999) 'Residual sum of squares = ', RSS
         WRITE (NOUT, 99998) 'Degrees of freedom = ', IDF
         WRITE (NOUT, *)
         WRITE (NOUT,*) 'Variable Parameter estimate Standard error'
         WRITE (NOUT, *)
         DO 60 J = 1, IP
            WRITE (NOUT, 99997) J, B(J), SE(J)
   60
         CONTINUE
         IFAIL = 0
         CALL GO2DGF(WEIGHT, N, WT, RSS, IP, IRANK, COV, Q, NMAX, SVD, P, NEWY, B,
                      SE, RES, WK, IFAIL)
         WRITE (NOUT, *)
         WRITE (NOUT,*) 'Results for second y-variable using GO2DGF'
         WRITE (NOUT, *)
         WRITE (NOUT, 99999) 'Residual sum of squares = ', RSS
         WRITE (NOUT, 99998) 'Degrees of freedom = ', IDF
         WRITE (NOUT, *)
         WRITE (NOUT,*) 'Variable Parameter estimate Standard error'
         WRITE (NOUT, *)
         DO 80 J = 1, IP
            WRITE (NOUT, 99997) J, B(J), SE(J)
   80
         CONTINUE
      END IF
      STOP
99999 FORMAT (1X,A,e12.4)
99998 FORMAT (1X,A,I4)
99997 FORMAT (1X,16,2e20.4)
      END
```

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## 9.2 Program Data

```
GO2DGF Example Program Data 12 4 'U' 'M'

1.0 0.0 0.0 0.0 33.63 63.0 0.0 0.0 1.0 39.62 69.0 0.0 1.0 0.0 38.18 68.0 0.0 0.0 1.0 0.0 41.46 71.0 0.0 0.0 0.0 1.0 38.02 68.0 0.0 1.0 0.0 0.0 1.0 35.83 65.0 0.0 0.0 0.0 1.0 35.99 65.0 1.0 0.0 0.0 0.0 36.58 66.0 0.0 0.0 1.0 0.0 42.92 72.0 1.0 0.0 0.0 0.0 37.80 67.0 0.0 0.0 1.0 0.0 40.43 70.0 0.0 1.0 0.0 0.0 37.89 67.0 1.0 1.1 1 1 5
```

# 9.3 Program Results

```
\begin{array}{lll} {\tt GO2DGF} \ {\tt Example} \ {\tt Program} \ {\tt Results} \\ {\tt Results} \ {\tt from} \ {\tt GO2DAF} \end{array}
```

```
Model not of full rank
```

```
Residual sum of squares = 0.2223E+02
Degrees of freedom = 8
```

Variable	Parameter estimate	Standard error
1	0.3056E+02	0.3849E+00
2	0.5447E+01	0.8390E+00
3	0.6743E+01	0.8390E+00
4	0.1105E+02	0.8390E+00
5	0.7320E+01	0.8390E+00

Results for second y-variable using GO2DGF

```
Residual sum of squares = 0.2400E+02
Degrees of freedom = 8
```

Variable	Parameter estimate	Standard error
1	0.5407E+02	0.4000E+00
2	0.1127E+02	0.8718E+00
3	0.1260E+02	0.8718E+00
4	0.1693E+02	0.8718E+00
5	0.1327E+02	0.8718E+00

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